

Detection unit : R1002CB(E)  
Control box : R1002CB(E)

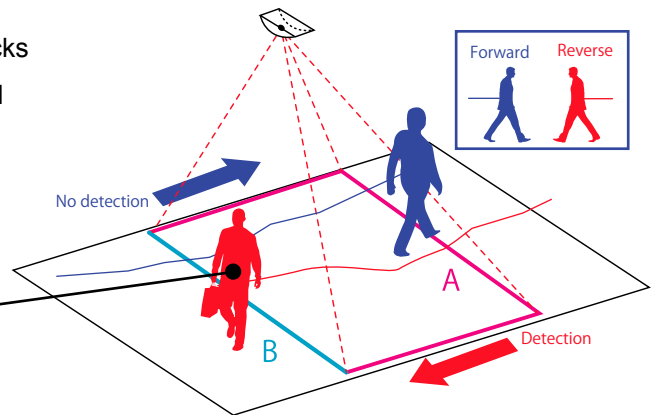
Reverse Detection System R1002 with an unique detection algorithm [ Vector Focal Method ] is designed to detect backward movement of human(s) in a specific area. The system are suitable for applications to catch a suspicious individual such as airports for an efficient facility management or security.



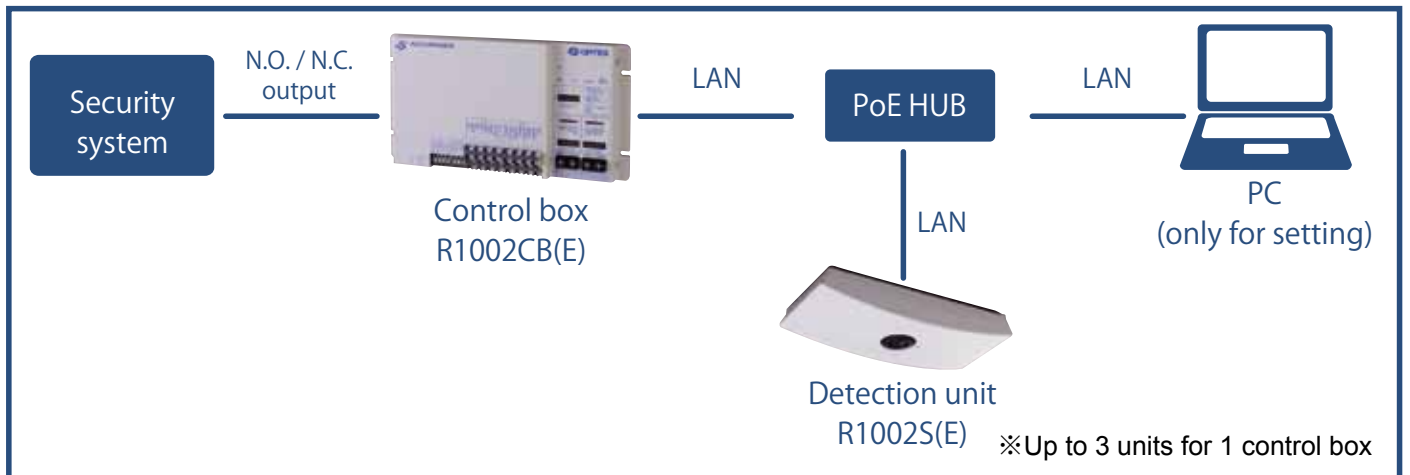
## Principle

An unique detection method [Vector Focal Method] grasps and tracks a shape of human sterically. The system can recognize complicated movement and the number of people at high rate and accuracy.

As shown in the figure below, when a passer by crosses two lines of pink (A) and light blue (B) in oppsite directions, a "Reverse" outout will be activated.



## System configuration



## Features

### Accurate detection

An unique detection method [Vector Focal Method] grasps and tracks a shape of human sterically.

### Reverse detection

Grasp all human movements and detect only backward movement

### System corporation

Enable to be connected with an upper layer system by using no-voltage output from the control box.

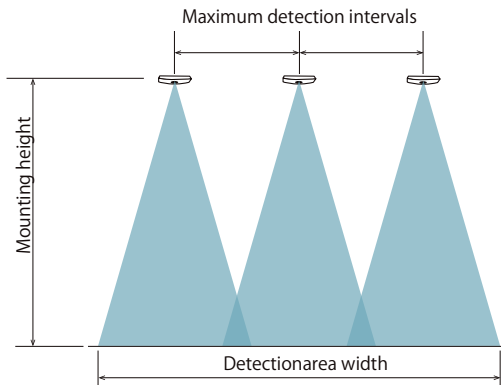
# Specifications

| Items                 | Specifications                    |  | Remarks  |
|-----------------------|-----------------------------------|--|--|
| Detection Method      | Vector Focusing Method            |  |  |
| Detection Accuracy    | > 95% (by own criteria)           |  |  |
| Supply Voltage        | Power over Ethernet IEEE 802.3 af |  |  |
| Warm-up time          | Approx. 45 sec.                   |  |  |
| Power Consumption     | Control box                       | 10 W max.  |  |
|                       | Detection unit                    | 10 W max.  |  |
| Indicator             | Control box                       | Green  | Power (lit)  |
|                       |                                   | Red  | Reverse detection (lit)  |
|                       |                                   | Green / Red  | Warm-up (lit) / Trouble (blinking)<br>Communication trouble (alternative blinking) |
|                       | Detection unit                    | Green  | Power (lit)  |
|                       |                                   | Red  | Reverse detection (lit)  |
|                       |                                   | Orange   | Warm-up (lit) / Trouble (blinking)<br>Communication trouble (alternative blinking) |
| Dimensions            | Control box                       | 265 × 135 × 31 mm  | (W × H × D)  |
|                       | Detection unit                    | 193 × 85 × 34 mm   | (W × H × D)  |
| Weight                | Control box                       | 800 g  |  |
|                       | Detection unit                    | 220 g  |  |
| Operating Temperature | 0 to 50°C                         |  |  |
| Operating Humidity    | < 80% RH                          |  | only under no condensation   |
| Operating Illuminance | 100 to 20,000 lux *1              |  | only the outline of an object is shown   |
| Install location      | Control box                       | Wall / stationary  | Interior only  |
|                       | Detection unit                    | Ceiling  | Interior only  |
| Mounting Height       | Detection unit                    | 2.5 to 4.0 m   | It may be limited by environmental conditions.                                     |
| LAN wiring            | CAT5e or larger                   |  | 100 m max. in length   |
| Ethernet              | 100Base-T(X)                      |  | Protocol : TCP/UDP(IPv4), ARP, ICMP or HTTP  |
| Input terminal *2     | Disable output                    | N.O./N.C. no voltage   | Disable reverse detection [1] and [2]  |
|                       | Output reset                      |  | Stop the outputs of reverse detection [1] and [2]                                  |
| Output terminal *2    | Reverse detection [1]             | MOS FET relay<br>N.O./N.C. no voltage<br>30 V DC 0.2 A or less<br>(Resistibility load) | Variable timer 0.2 to infinity   |
|                       | Reverse detection [2]             |  | Pulse output for reverse detection by unit [1]                                     |
|                       | Unit [1] detects                  |  | Pulse output for reverse detection by unit [2]                                     |
|                       | Unit [2] detects                  |  | Pulse output for reverse detection by unit [3]                                     |
|                       | Unit [3] detects                  |  | Pulse output for the number of reverse detection                                   |
|                       | Number of reverse detections      |  | Output when disable to detect  |
|                       | Error                             |  |  |

\*1 R1002 always requires 100 lux or more.

\*2 Input/output relays can be selected N.O./N.C. by the dipswitch.

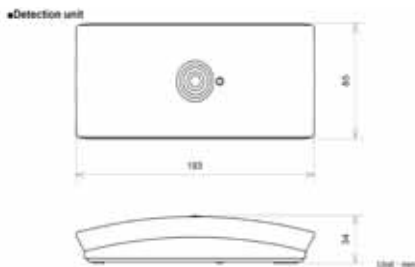
## Detection area



| Mounting height | Detection area width |           |             | Maximum installation intervals |
|-----------------|----------------------|-----------|-------------|--------------------------------|
|                 | One unit             | Two units | Three units |                                |
| 2500            | 1500                 | 2700      | 3900        | 1200                           |
| 3000            | 2700                 | 5100      | 7500        | 2400                           |
| 3500            | 3300                 | 6300      | 9300        | 3000                           |
| 4000            | 4000                 | 7700      | 11400       | 3700                           |

Unit : mm

## Dimensions



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